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CS-104

Algorithm (Accuracy)

1. Start Robot
2. Roll 360° at 48 speed for 3 secs
3. Roll -360° at 48 speed for 3 secs
4. Loop 5 times
5. Input speech “I am the winner”
6. Input robot color to “Blue” for 1 sec 1 time
7. Input robot color to “Green” for 1 sec 1 time
8. Input robot color to “Red” for 1 sec 1 time
9. Input robot color to “Violet” for 1 sec 1 time
10. Input robot color to “Yellow” for 1 sec 1 time
11. End program